

Math 482: Topics Covered in Exam 1

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The first exam will, broadly speaking, cover all the material covered in class through Monday, February 17th. This includes general intro material to linear programs, and all topics related to the simplex method.

Below I try to summarize the important things we've covered that will be on the exam. It's possible that I've missed a few topics, and it's hard to summarize three weeks of content in two pages anyway; if you're not sure about something, ask me.

1 Things you should know

Here are the definitions you should know:

- The **objective value**, **constraints**, **feasible solutions**, **optimal solutions**, and **feasible region** of a linear program.
- **Convex sets**, **vertices**, and **extreme points**.
- The **basic variables**, **nonbasic variables**, **basic feasible solution**, **reduced costs** of a simplex method tableau.
- **Slack variables** and (for the two-phase simplex method) **artificial variables**.
- **Unbounded** and **inconsistent** linear programs.
- **Degenerate pivots**, **cycling**, and **pivot rules**.
- Specific pivot rules: the **largest/most negative reduced cost rule**, **Bland's rule**, **lexicographic pivoting**.

You should know and understand the following results about linear programs:

- If the feasible region of a linear program is nonempty and bounded, then the linear program has an optimal solution, and at least one optimal solution is a basic feasible solution.
- The vertices/extreme points of the feasible region are precisely the basic feasible solutions of the linear program.
- In non-degenerate cases, the simplex method is guaranteed to produce better and better solutions, and when it stops, it finds an optimal solution.
- Both Bland's rule and the lexicographic pivoting rule prevent cycling.

- Both Bland’s rule and the lexicographic pivoting rule can be tricked into checking exponentially many corner points, in the worst case.
- Formulas for the pieces of a simplex tableau: \mathbf{p} , Q , \mathbf{r}^\top , and z_0 (in the notation of Lecture 9).

2 Things you should be able to do

Represent a word problem as a linear program.

Convert between different forms of a linear program:

- Turn inequalities into equations and equations into inequalities.
- Convert a program with unconstrained variables to one with nonnegative variables.
- Convert a minimization problem into a maximization problem.

Skills related to the simplex method. (You can probably summarize most of these as “be able to use the simplex method”, but maybe you’d appreciate specifics.)

- Read off the basic feasible solution and objective value in a tableau.
- Move between valid tableaus by pivoting on variables.
- Choose entering variables (based on the objective function) and leaving variables (based on the nonnegativity constraints).
- Notice when a tableau represents an optimal solution.
- Notice when a linear program is unbounded, and find a ray of feasible solutions along which the objective value improves without bound.
- For linear programs with constraints $\{A\mathbf{x} \leq \mathbf{b}, \mathbf{x} \geq \mathbf{0}\}$ in which $\mathbf{x} = \mathbf{0}$ is feasible, use the slack variables to write down an initial feasible solution.
- For general linear programs, use the two-phase simplex method to find an initial tableau.
- When using the two-phase simplex method, notice when the linear program is infeasible.
- Use the most negative reduced cost rule (when minimizing) to choose entering variables.
- Use Bland’s rule to choose entering and leaving variables.
- Use the lexicographic pivoting rule (introducing $\epsilon_1, \dots, \epsilon_m$) to choose leaving variables.

You should be able to use the revised simplex method instead of a tableau, computing and updating the matrix A_B^{-1} and the vector $A_B^{-1}\mathbf{b}$, and finding reduced costs on the fly.

In general, unless I specify a pivoting rule I want you to use, you can make any (valid) choices of entering and leaving variables you like when solving a linear program.