

Practice problems -Solutions

1) Recall the definition of linearly independent vectors.

Solutions The vectors v_1, \dots, v_m are linearly independent if

$$\sum_j \lambda_j v_j = 0$$

only occurs for $\lambda_1 = \dots = \lambda_m = 0$. If v_1, \dots, v_m are in \mathbb{R}^k then this is the case iff and only if the determinant of the matrix of inner products

$$m_{ij} = v_i \cdot v_j$$

is non-0.

2) Differentiate

$$f(x) = \frac{\partial}{\partial x} \int_0^{x^2+y^2} (x^2 + y^3)^{1/3} dy .$$

Solution: We introduce

$$F(x, z) = \int_0^z (x^2 + y^3)^{1/3} dy$$

and find

$$f(x) = F(x, x^2)$$

and hence

$$\begin{aligned} f'(x) &= \frac{\partial F}{\partial x}(x, x^2) + \frac{\partial F}{\partial z}(x, x^2)2x \\ &= \int_0^{x^2} 1/3(x^2 + y^3)^{-2/3}2x dy + (x^2 + x^6)^{1/3}2x \\ &= 2x \left(\int_0^{x^2} 1/3(x^2 + y^3)^{-2/3} dy + x^{2/3}(1 + x^4)^{1/3} \right) . \end{aligned}$$

Calculate the area of the Archimedean spiral.

Solution: We have $r(\theta) = a\theta$ and hence the boundary of one cycle is given by

$$g(\theta) = r(\theta) \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix} = a\theta \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix} .$$

We may integrate xdy and deduce from Green (and

$$dy = d(a\theta \sin \theta) = a \sin \theta + a\theta \cos \theta)$$

that

$$\begin{aligned} \text{area}(sp) &= \int_0^{2\pi} a\theta \cos(\theta)(a \sin \theta + a\theta \cos \theta)d\theta \\ &= a^2 \int_0^{2\pi} \theta \sin \theta \cos \theta d\theta + a^2 \int_0^{2\pi} \theta^2 \cos^2(\theta)d\theta . \end{aligned}$$

Time for integration by parts.

$$2 \int_0^{2\pi} \theta \sin \theta \cos \theta d\theta = \theta \sin^2 \theta \Big|_0^{2\pi} - \int_0^{2\pi} \sin^2 \theta d\theta = -\pi .$$

Moreover,

$$\begin{aligned} \int \cos^2 \theta d\theta &= \int \cos \theta \cos \theta d\theta \\ &= \sin \theta \cos \theta + \int \sin \theta \sin \theta \\ &= \sin \theta \cos \theta + \theta - \int \cos^2 \theta . \end{aligned}$$

Hence

$$\int \cos^2 \theta d\theta = \frac{\sin \theta \cos \theta + \theta}{2} .$$

This gives

$$\begin{aligned} \int_0^{2\pi} \theta^2 \cos^2(\theta)d\theta &= \frac{\sin \theta \cos \theta + \theta}{2} \theta^2 \Big|_0^{2\pi} - \int 2\theta \frac{\sin \theta \cos \theta + \theta}{2} \\ &= \frac{(2\pi)^3}{2} - \int_0^{2\pi} \theta^2 d\theta - \int \theta \sin \theta \cos \theta d\theta \\ &= \frac{(2\pi)^3}{6} - \int_0^{2\pi} \theta \sin \theta \cos \theta d\theta \\ &= \frac{(2\pi)^3}{6} + \frac{\pi}{2} . \end{aligned}$$

Thus we get

$$a^2 \left(\frac{(2\pi)^3}{6} \right) .$$

3)

1. Calculate the flux

$$\int_G F \cdot ndS .$$

a) $F(x_1, x_2, x_3) = \begin{pmatrix} x_1^2 x_2 \\ x_2^2 x_3 \\ x_3^2 x_1 \end{pmatrix}$ and G is the upper hemisphere with radius

1.

b) $G = \left\{ \begin{pmatrix} y_1^3 - y_2 \\ y_2^3 - y_3 \\ y_3 \end{pmatrix} : y_1^2 + y_2^2 + y_3^2 = 1 \right\}$ and $F(x_1, x_2, x_3) = \begin{pmatrix} x_1 \\ 0 \\ 0 \end{pmatrix}$.

You may use $\int_0^{2\pi} \cos^4(\phi) d\phi = \frac{3\pi}{4}$ and $\int_0^\pi \sin^4 \theta d\theta = \frac{3\pi}{8}$.

Solution: Let K the half ball. Then we note that

$$F \cdot \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = x_3^2 x_1 = 0.$$

Thus, by the divergence theorem

$$\int_G F \cdot ndS = \int_K (2x_1x_2 + 2x_2x_3 + 2x_3x_1) d(x_1, x_2, x_3) = 0.$$

Indeed, we may change x_1 to $-x_1$ without changing the body. Hence the first and the third term are 0. We repeat this for x_2 and get the result. For part b) we change in into a differential form

$$\omega = x_1 dx_2 \wedge dx_3$$

and use the change of variable

$$x_1 = y_1^3 - y_2 \quad x_2 = y_2^3 - y_3 \quad x_3 = y_3.$$

This gives $dx_2 = 3y_2^2 dy_2 - dy_3$, $dy_3 = dx_3$ and hence

$$x_1 dx_2 \wedge dx_3 = (y_1^3 - y_2) dy_2 \wedge dy_3$$

Now we have to use the standard parametrization of the sphere $g(\theta, \phi) = \begin{pmatrix} \sin \theta \cos \phi \\ \sin \theta \sin \phi \\ \cos \theta \end{pmatrix}$

with

$$\det g'_{23} = \sin^2 \theta \cos \phi.$$

This gives

$$\begin{aligned}
 \int_G F \cdot ndS &= \int_{y_1^2+y^2+y_3^2=1} (y_1^3 - y_2) dy_2 \wedge dy_3 \\
 &= \int_0^{2\pi} \int_0^\pi (\sin^3 \theta \cos^3 \phi - \sin \theta \sin \phi) \sin^2 \theta \cos \phi d\theta d\phi \\
 &= \int_0^{2\pi} \int_0^\pi \sin^4 \theta \cos^4 \phi d\theta d\phi \\
 &= \int_0^{2\pi} \cos^4 \phi d\phi \int_0^\pi \sin^4 \theta d\theta .
 \end{aligned}$$

By the hint we get $9/32\pi^2$.

6. Derive the divergence theorem from the general Stokes theorem.

Solution: Let

$$\omega = F_1 dx_2 \wedge dx_3 + F_2 dx_3 \wedge dx_1 + F_3 dx_1 \wedge dx_2$$

be a differential form of degree 2. Then

$$d\omega = \left(\frac{\partial F_1}{\partial x_1} + \frac{\partial F_2}{\partial x_2} + \frac{\partial F_3}{\partial x_3} \right) dx_1 \wedge dx_2 \wedge dx_3 .$$

By the general Stokes theorem we have

$$\int_K \operatorname{div}(F) d\operatorname{vol} = \int_K d\omega = \int_{\partial K} \omega$$

provided the boundary is outward oriented. Let $g : D \rightarrow \mathbb{R}^3$ be a parametrization with coordinate function g_1, g_2, g_3 . Then we observe that

$$\frac{\partial g}{\partial s} \times \frac{\partial g}{\partial t} = \begin{pmatrix} \frac{\partial g_2}{\partial s} - \frac{\partial g_3}{\partial t} \\ \frac{\partial g_3}{\partial s} - \frac{\partial g_1}{\partial t} \\ \frac{\partial g_1}{\partial s} - \frac{\partial g_2}{\partial t} \end{pmatrix} = \begin{pmatrix} \det g'_{23} \\ \det g'_{31} \\ \det g'_{12} \end{pmatrix} .$$

Thus by the definition we deduce that indeed

$$\int_{\partial K} d\omega = \int_D F(\gamma(s, t)) \cdot N(s, t) dA(s, t) = \int F \cdot ndS .$$

7. Calculate in two different ways

$$\int_{-1 \leq x_1 \leq 1, 0 \leq x_2 \leq 1-x_1^4, x_3=1-x_1^4-x_2} x_1^3 dx_2 \wedge dx_3 .$$

Solution: We use $\omega = x_1^3 dx_2 \wedge dx_3$ and

$$d\omega = 3x_1^2 dx_1 \wedge dx_2 \wedge dx_3.$$

By the divergence theorem we deduce for

$$K = \left\{ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} : -1 \leq x_1 \leq 1, 0 \leq x_2 \leq 1 - x_1^4, 0 \leq x_3 \leq 1 - x_1^4 - x_2 \right\}$$

that

$$\begin{aligned} \int_K d\omega &= \int_{-1}^1 \int_0^{1-x_1^4} \int_0^{1-x_1^4-x_2} 3x_1^2 dx_3 dx_2 dx_1 \\ &= 3 \int_{-1}^1 \int_0^{1-x_1^4} (1 - x_1^4 - x_2) dx_2 x_1^2 dx_1 \\ &= 3 \int_{-1}^1 (1 - x_1^4)^2 - \frac{(1 - x_1^4)^2}{2} x_1^2 dx_1 \\ &= \frac{3}{2} \int_{-1}^1 (1 - x_1^4)^2 x_1^2 dx_1 \\ &= 3 \int_0^1 (1 - 2x_1^4 + x_1^8) x_1^2 dx_1 \\ &= 3 \left(\frac{1}{3} - \frac{2}{7} + \frac{1}{11} \right) = \frac{77 - 66 + 21}{77} = \frac{32}{77}. \end{aligned}$$

However, we have to be careful with two other pieces of the boundary. On in front in the x_1, x_3 plane. In the x_2, x_3 plane we have $x_1 = 0$ and hence

$$\int_K d\omega = \int_{\partial K_f} \omega = \int_{-1 \leq x_1 \leq 1, 0 \leq x_2 \leq 1 - x_1^4, x_3 = 1 - x_1^4 - x_2} x_1^2 dx_2 \wedge dx_3.$$

The other possibility is the definition. We use $h(x_1, x_2) = 1 - x_1^4 - x_2$ and

$$g(x_1, x_2) = \begin{pmatrix} x_1 \\ x_2 \\ h(x_1, x_2) \end{pmatrix}.$$

We get

$$\det g'_{23} = \det \begin{pmatrix} 0 & 1 \\ \frac{\partial h}{\partial x_1} & \frac{\partial h}{\partial x_2} \end{pmatrix} = -\frac{\partial h}{\partial x_1} = 4x_1^3.$$

This gives

$$\begin{aligned} \int_{-1 \leq x_1 \leq 1, 0 \leq x_2 \leq 1-x_1^4, x_3=1-x_1^4-x_2} x_1^3 dx_2 \wedge dx_3 &= \int_{-1 \leq x_1 \leq 1, 0 \leq x_2 \leq 1-x_1^4} x_1^3 (4x_1^3) dx_2 dx_1 \\ &= 4 \int_{-1}^1 (1-x_1^4) x_1^6 dx_1 \\ &= 8 \int_0^1 (x_1^6 - x_1^{10}) dx_1 = 8 \left(\frac{1}{7} - \frac{1}{11} \right) = 8 \left(\frac{11-7}{77} \right) = \frac{32}{77}. \end{aligned}$$

Pretty cool.

8. 5) Let

$$G = \left\{ \begin{pmatrix} y_1 - y_2^2 \\ y_2 \\ y_3 \end{pmatrix} : y_1^2 + y_2^2 + y_3^2 = 1, y_1 \geq 0 \right\}$$

and $F(x_1, x_2, x_3) = \begin{pmatrix} x_3 \\ 0 \\ 0 \end{pmatrix}$. Calculate in two different ways

$$\int_G \text{curl}(F) \cdot ndS.$$

Solution: Let $\omega = x_3 dx_1$ and

$$x_1 = y_1 - y_2^2, x_2 = y_2, x_3 = y_3$$

the change of variables. We get

$$\omega = y_3 d(y_1 - y_2^2) = y_3 dy_1 - 2y_3 y_2 dy_2$$

Then Stokes theorem (together with $dy_1 = 0 = y_1$, $y_2 = \cos \theta$, $y_3 = \sin \theta$) gives

$$\begin{aligned} \int_G \text{curl}(F) \cdot ndS &= \int_{\partial G} \omega \cdot T ds \\ &= \int_0^{2\pi} -2 \sin \theta \cos \theta (-\sin \theta) d\theta = 0. \end{aligned}$$

As for the surface integral we have

$$d\omega = dx_3 \wedge dx_1 = dy_3 \wedge dy_1 - 2y_2 dy_3 \wedge dy_2.$$

We use $g(\theta, \phi) = \begin{pmatrix} \cos \theta \\ \sin \theta \cos \phi \\ \sin \theta \sin \phi \end{pmatrix}$ with

$$g'(\theta, \phi) = \begin{pmatrix} -\sin \theta & 0 \\ \cos \theta \cos \phi & \sin \theta (-\sin \phi) \\ \cos \theta \sin \phi & \sin \theta \cos \phi \end{pmatrix}.$$

and get

$$\det g'_{31} = \sin^2 \theta \cos \phi, \quad \det g'_{23} = \cos \theta \sin \theta.$$

This gives $0 \leq \theta \leq \pi/2$, $0 \leq \phi \leq 2\pi$,

$$\int_G d\omega = \int_0^{\pi/2} \int_0^{2\pi} [\sin^2 \theta \cos \phi + 2 \sin \theta \cos \phi \cos \theta \sin \theta] d\phi d\theta = 0.$$

9. Decide whether the following vector fields are conservative

a) $F(x_1, x_2) = \begin{pmatrix} x_1^2 x_2^3 \\ x_1^3 x_2^2 \end{pmatrix}.$

b) $F(x_1, x_2, x_3) = \begin{pmatrix} \cos(x_1^2 x_2^2 x_3^2) 2x_1 \\ \cos(x_1^2 x_2^2 x_3^2) 2x_2 \\ \cos(x_1^2 x_2^2 x_3^2) 2x_3 \end{pmatrix}.$

Solution: In a) we have to $\frac{\partial Q}{\partial x_1} = \frac{\partial P}{\partial x_2}$. In our case

$$\frac{\partial Q}{\partial x_1} = 3x_1^2 x_2^2 = \frac{\partial P}{\partial x_2}.$$

For Problem b) we have to check three of these:

$$\begin{aligned} \text{curl}(F) &= \begin{pmatrix} \frac{\partial}{\partial x_1} \\ \frac{\partial}{\partial x_2} \\ \frac{\partial}{\partial x_3} \end{pmatrix} \times \begin{pmatrix} \cos(x_1^2 x_2^2 x_3^2) 2x_1 \\ \cos(x_1^2 x_2^2 x_3^2) 2x_2 \\ \cos(x_1^2 x_2^2 x_3^2) 2x_3 \end{pmatrix} \\ &= \begin{pmatrix} (-4)x_2 x_3 \sin(x_1^2 x_2^2 x_3^2) - (-4)(x_2 x_3) \sin(x_1^2 x_2^2 x_3^2) \\ (-4)x_1 x_3 \sin(x_1^2 x_2^2 x_3^2) - (-4)x_1 x_3 \sin(x_1^2 x_2^2 x_3^2) \\ (-4)x_1 x_2 \sin(x_1^2 x_2^2 x_3^2) - (-4)x_1 x_2 \sin(x_1^2 x_2^2 x_3^2) \end{pmatrix} \end{aligned}$$

which of course is 0.