

The spanning problem in 2D

Problem Given two vectors v, w in \mathbb{R}^2 .

When is it true that for all z in \mathbb{R}^2

we can find λ, μ such that

$$(*) \quad z = \lambda v + \mu w \quad ?$$

Examples 1) $v = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad w = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

2) $v = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad w = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$

3) $v = \begin{pmatrix} 1 \\ 2 \end{pmatrix} \quad w = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$

4) $v = \begin{pmatrix} 1 \\ 2 \end{pmatrix} \quad w = \begin{pmatrix} -2 \\ -4 \end{pmatrix}$

Answer : If v, w do not point in same direction up to sign π

Def $\lambda v, w$ is called a basis for \mathbb{R}^2 if

- every point can be expressed by $(*)$

Problem II Let z, w be a basis.

How can we find λ, μ ?

$$z = \begin{pmatrix} x \\ y \end{pmatrix}$$

Answer: Solve linear equation $v = \begin{pmatrix} a_{11} \\ a_{21} \end{pmatrix}$ $w = \begin{pmatrix} a_{12} \\ a_{22} \end{pmatrix}$

$$x = \lambda a_{11} + \mu a_{12}$$

$$y = \lambda a_{21} + \mu a_{22}$$

Examples

$$\begin{pmatrix} 3 \\ 7 \end{pmatrix} = \lambda \begin{pmatrix} 1 \\ 2 \end{pmatrix} + \mu \begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

$$\begin{aligned} \lambda + \mu &= 3 \\ 2\lambda + 3\mu &= 7 \end{aligned}$$

$$\mu = 3 - \lambda$$

$$7 = 2\lambda + 3(3 - \lambda)$$

$$= 9 - \lambda$$

$$\lambda = 2 \quad \mu = 1$$

General method

Definition An $n \times m$ matrix is a collection

1) of $n \cdot m$ real numbers

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1m} \\ a_{21} & & & \\ \vdots & & & \\ a_{n1} & & & a_{nm} \end{bmatrix}$$

2) Let $x = \begin{pmatrix} x_1 \\ \vdots \\ x_m \end{pmatrix}$ be a vector in m -space.

$$\text{Then } Ax = \begin{bmatrix} a_{11}x_1 + \dots + a_{1m}x_m \\ \vdots \\ a_{n1}x_1 + \dots + a_{nm}x_m \end{bmatrix}$$

is a vector in n -space

3) One can multiply a $n \times m$ matrix with a $m \times k$ matrix and get a $n \times k$ matrix

$$A \cdot B = \begin{bmatrix} a_{11}b_{11} + \dots + a_{1m}b_{m1} & \dots & a_{11}b_{1k} + \dots + a_{1m}b_{mk} \\ \vdots & \ddots & \vdots \\ a_{n1}b_{11} + \dots + a_{nm}b_{m1} & \dots & a_{n1}b_{1k} + \dots + a_{nm}b_{mk} \end{bmatrix}$$

How helpful?

Observation:

$$z = \lambda v + \mu w$$

$$\text{means } z = a \begin{pmatrix} \lambda \\ \mu \end{pmatrix} \quad a = (v \ w)$$

If we can find C such that

$$Ca = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \text{ then}$$

$$C(z) = Ca \begin{pmatrix} \lambda \\ \mu \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \lambda \\ \mu \end{pmatrix} = \begin{pmatrix} \lambda \\ \mu \end{pmatrix}$$

Hence λ, μ are given by $C(z)$!

We traded ~~our~~ Problem II against

Problem III Find C with $Ca = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$!

Note Pb II and Pb III are really equivalent

(equally difficult) if we look for

- a general algorithm which works for all z (HW)

Key Example

$$\begin{pmatrix} a & b \\ 0 & c \end{pmatrix} \begin{pmatrix} e & f \\ g & h \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

Then $0 \cdot f + ch = 1$ $h = \frac{1}{c}$

$0 \cdot e + cg = 0$ $g = 0$
 $= 0$

$ae = 1$ $e = \frac{1}{a}$

$a\cancel{f} + bh = 0$

$f = -\frac{bh}{a} = -\frac{b}{ac}$

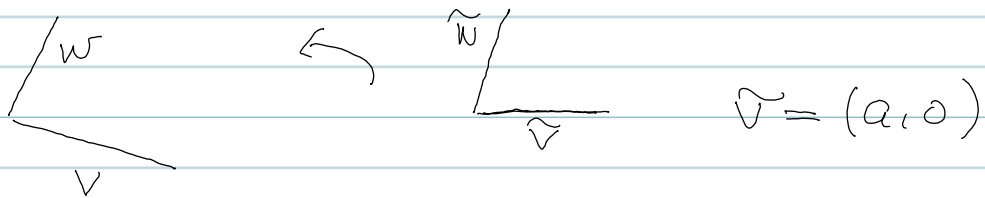
Solution is

$$\begin{pmatrix} a & b \\ 0 & c \end{pmatrix} \begin{pmatrix} \frac{1}{a} & -\frac{b}{ac} \\ 0 & \frac{1}{c} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\boxed{a^{-1} = \frac{1}{a} \begin{pmatrix} c & -b \\ 0 & a \end{pmatrix}}$$

↑
The inverse of a

Q General case?



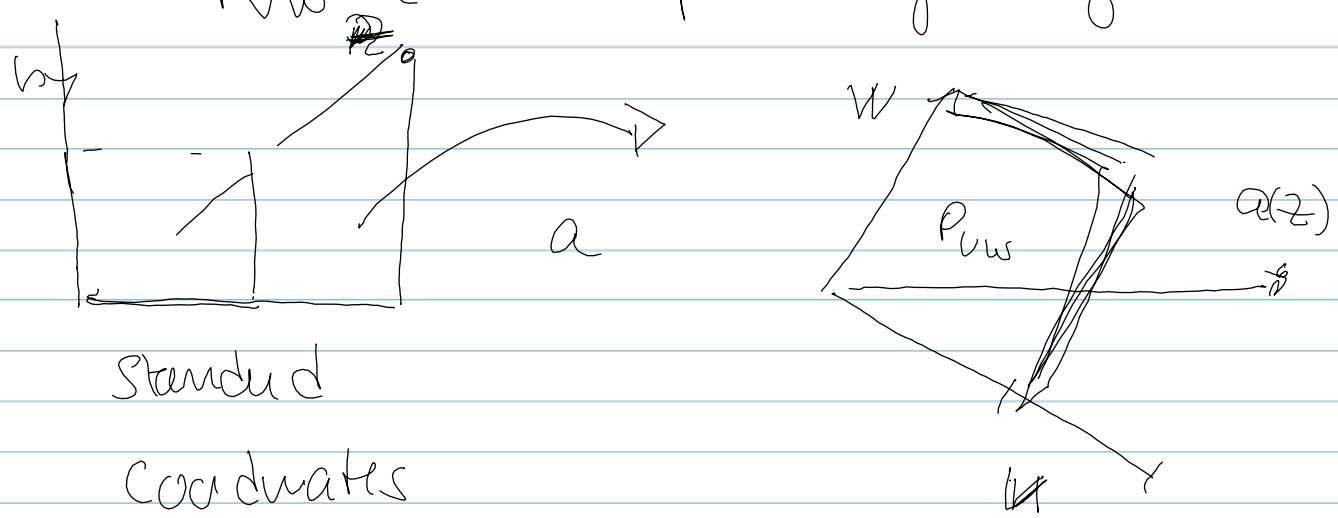
A new matrix $M = \begin{pmatrix} v_1 & w_1 \\ v_2 & w_2 \end{pmatrix}$

$\tilde{M} = \begin{pmatrix} \tilde{v}_1 & \tilde{w}_1 \\ \textcircled{0} & \tilde{w}_2 \end{pmatrix}$. ← Here we know what to do.

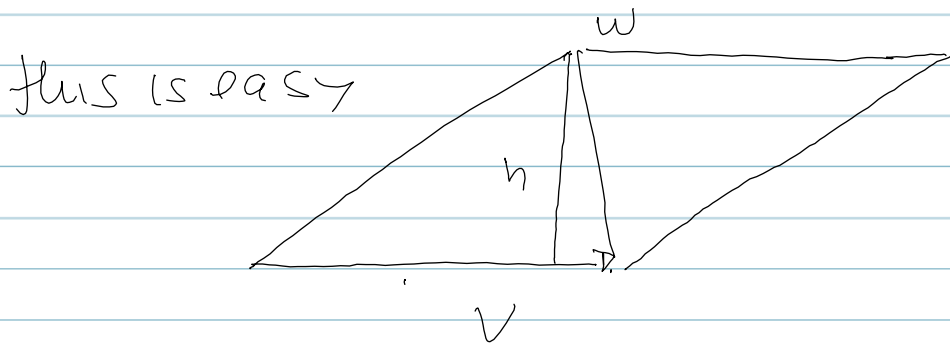
Determinants and area

Pb IV Let $\{v, w\}$ be a basis a and b

P_{vw} be the unit parallelogram given



Again for $v = \begin{pmatrix} \alpha \\ 0 \end{pmatrix}$ $w = \begin{pmatrix} \beta \\ \gamma \end{pmatrix}$



$$\text{Area} = \frac{1}{2} \times \text{base} \times \text{height} = \text{base} \times \text{height} \\ = \alpha \beta$$

Theorem The area of P_{wv} is given
by the

provided $\begin{vmatrix} a_{11} & a_{22} \\ a_{12} & a_{21} \end{vmatrix}$

$$v = \begin{pmatrix} a_{11} \\ a_{21} \end{pmatrix} \quad w = \begin{pmatrix} a_{12} \\ a_{22} \end{pmatrix}$$

(This means

$$v = a \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad w = a \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$\begin{pmatrix} 1 \\ 0 \end{pmatrix}$ $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$ are called ^{standard} unit vectors

Definition: $A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$ be a 2×2 matrix, then the determinant of A is given by

$$\det(A) = a_{11}a_{22} - a_{12}a_{21}$$

(This means $\det(P_{uv}) = |\det(A)|$)

Lemma $\det(ab) = \det(a) \det(b)$

Proof $a = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \quad b = \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix}$

$$\det(a) \det(b) = (a_{11}a_{22} - a_{12}a_{21})(b_{11}b_{22} - b_{12}b_{21})$$

$$= a_{11}a_{22}b_{11}b_{22} + a_{12}a_{21}b_{12}b_{21}$$

$$- a_{11}a_{22}b_{12}b_{21} - a_{12}a_{21}b_{11}b_{22}$$

$$ab = \begin{pmatrix} a_{11}b_{11} + a_{12}b_{21} & a_{11}b_{12} + a_{12}b_{22} \\ a_{21}b_{11} + a_{22}b_{21} & a_{21}b_{12} + a_{22}b_{22} \end{pmatrix}$$

$$\det(ab) = (a_{11}b_{11} + a_{12}b_{21})(a_{21}b_{12} + a_{22}b_{22}) - (a_{11}b_{12} + a_{12}b_{22})(a_{21}b_{11} + a_{22}b_{21})$$

$$= \underbrace{a_{11}a_{21}b_{11}b_{12}} + a_{11}a_{22}b_{11}b_{22} + a_{12}a_{21}b_{21}b_{12} + \underbrace{a_{12}b_{21}a_{22}b_{22}} - \underbrace{a_{11}a_{21}b_{12}b_{11}} - a_{11}a_{22}b_{12}b_{21} - a_{12}a_{21}b_{22}b_{11} - \underbrace{a_{12}a_{22}b_{22}b_{21}}$$

$$= a_{11}a_{22}b_{11}b_{22} + a_{12}a_{21}b_{21}b_{12} - a_{11}a_{22}b_{12}b_{21} - a_{12}a_{21}b_{11}b_{22}$$

$$= \det(a) \det(b)$$



clockwise rotation

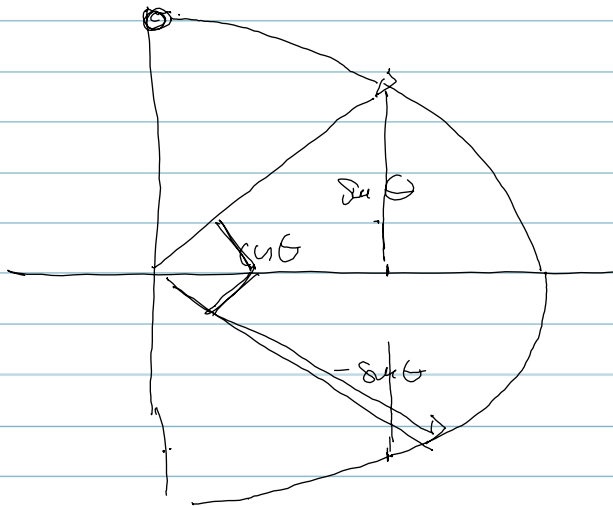
Fact The matrix of a rotation is given

$$\text{by } u_{\theta} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$$

and satisfies

$$\det(u_{\theta}) = 1$$

$$u_{\theta} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} \cos \theta \\ -\sin \theta \end{pmatrix} \quad u_{\theta} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} \sin \theta \\ \cos \theta \end{pmatrix}$$



Proof of Thm Let v, w be given

Choose u_Θ such that

$$\forall u_\Theta (v) = \begin{pmatrix} \alpha \\ 0 \end{pmatrix} \quad u_\Theta w = \widetilde{w}$$

Then the new matrix is $\widetilde{a} = \begin{pmatrix} \alpha & \beta \\ 0 & \gamma \end{pmatrix}$ and

$$\text{area}(P_{v,w}) = \text{area } P_{\widetilde{v}, \widetilde{w}}$$

$$\text{area is } |\alpha\gamma| \\ = |\det \widetilde{a}|$$

$$= |\det \widetilde{a}|$$

$$= |\det u_\Theta a|$$

$$= |\det u_\Theta| |\det a|$$

$$= 1$$

$$= |\det a|$$



Theorem $a^{-1} = \frac{1}{\det a} \begin{pmatrix} \delta & -\beta \\ -\gamma & \alpha \end{pmatrix}$

(Let $a = \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix}$, then)

Proof $\begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} \begin{pmatrix} \delta & -\beta \\ -\gamma & \alpha \end{pmatrix} = \begin{pmatrix} \alpha\delta - \beta\gamma & \alpha\beta - \beta\alpha \\ \gamma\delta - \delta\gamma & \alpha\delta - \beta\gamma \end{pmatrix}$

$$= \begin{pmatrix} \det(a) & 0 \\ 0 & \det(a) \end{pmatrix}$$

