

# LINEAR INDEPENDENCE

and

## HIGHER DIMENSION

A set  $\{v_1, \dots, v_k\}$  in  $\mathbb{R}^n$  (or some vector space) is called linearly independent if

$$\sum d_j v_j = 0 \quad \text{implies} \quad d_j = 0 \quad \text{for } j=1, \dots, k.$$

A set  $\{v_1, \dots, v_k\} \in \mathbb{R}^n$  is called a basis if for every  $x \in \mathbb{R}^n$  there is a unique way of writing

$$x = \sum_{j=1}^k d_j v_j \quad \text{with } d_j \in \mathbb{R}$$

Pb Given  $v_1, \dots, v_k \in \mathbb{R}^n$  how can we check that  $v_1, \dots, v_k$  are linearly independent?

Motivation: ( $k=n$ ) for calculus

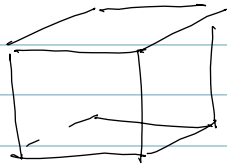
Let  $A: \mathbb{R}^k \rightarrow \mathbb{R}^n$  be the matrix such that

$$\left[ A \begin{pmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix} \right]_{\text{row } j} = v_j$$

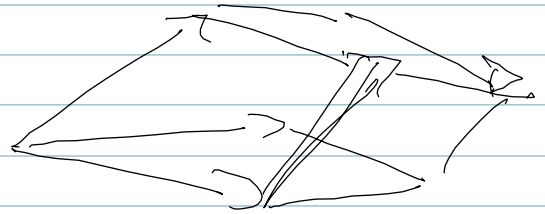
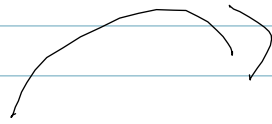
Then

$$\text{Vol}_k \{ \sum_{j=1}^k \lambda_j v_j : 0 \leq \lambda_j \leq 1 \}$$
$$= |\det a|$$

$a$



unit cube



parallelepiped.

Solution 1 (Pb)

Consider the matrix  $B = (v_i \cdot v_j)_{1 \leq i, j \leq k}$ .

then  $v_1, \dots, v_k$  are linearly independent if and only if

$$\det(B) > 0$$

Recall the inductively defined determinant formula

$$\det A = \sum_{j=1}^n (-1)^{i+j} a_{ij} \det(A_{i,j}^{i,j})$$

where  $A_{i,j}^{i,j}$  is the matrix obtained by erasing the  $i$ -th row and  $j$ -th column.

Ex

$$\begin{aligned} \det \begin{pmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{pmatrix} &= 1 \cdot \overset{-3}{(45-48)} - 2 \overset{-6}{(36-42)} + 3 \overset{-3}{(32-35)} \\ &= 1(-3) - 2(-6) + 3(-3) \\ &= -3 + 12 - 9 = 0 \end{aligned}$$

## Solution 2 GRAM-SCHMIDT-METHOD

Given  $v_1, \dots, v_k$

Output a)  $w_1, \dots, w_k$

b)  $n_1, \dots, n_k$ .

Step 1

$$w_1 = v_1$$

Step 2  $w_2 = v_2 - P_{w_1}(v_2)$   $w_2 = 0$  Stop

⋮

Step k  $w_k = v_k - P_{w_1}(v_k) - \dots - P_{w_{k-1}}(v_k)$

$w_k \neq 0$  Stop

If  $w_k \neq 0$  and program did not stop,

then  $v_1, \dots, v_k$  are linearly independent.

Then we can produce

$$n_j = \frac{w_j}{|w_j|} \quad \text{which have}$$

the property  $|n_j| = 1$   $n_j \cdot n_l = 0$   $j \neq l$

## Properties

a) If  $w_j$  are never 0, then  $v_1, \dots, v_n$  are lin. indep

$$b) w_j = v_j + \sum_{i=1}^{j-1} \alpha_{ij} v_i$$

$$c) v_j = w_j + \sum_{i=1}^{j-1} \beta_{ij} w_i$$

d) let  $a$  be the matrix such that  $a(e_j) = v_j$

and  $b$  be the matrix such that  $b(e_j) = w_j$

Then there exists an upper triangular matrix  $\alpha$

$$\alpha_{ij} = \begin{pmatrix} 1 & * \\ 0 & \dots \\ & & 1 \end{pmatrix} \text{ such that}$$

$$\boxed{b = \alpha a}$$

c) In particular  $\det(b) = \det(a)$  (because  $\det(\alpha) = 1$ )

e) The matrix  $b$  is easy to invert. Indeed

$$x = \sum \alpha_j w_j, \text{ then } \boxed{\alpha_j = \frac{x \cdot w_j}{w_j \cdot w_j}}$$

gives the unique coefficients.

$$f) \{ \sum \alpha_j v_j : \alpha_j \in \mathbb{R} \} = \{ \sum \alpha_j w_j : \alpha_j \in \mathbb{R} \}$$

Same Span

Problem: let  $S$  be given by

$$x^2 + y^2 - z^2 - w^2 = 5$$

Find an orthonormal basis for the tangent space

Solution: We understand  $S$  as a surface of the function

$$w = f\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \sqrt{x^2 + y^2 - z^2 - 5}$$

Then the tangent space is given by the span of vectors

$$\begin{pmatrix} 1 \\ 0 \\ 0 \\ \frac{\partial f}{\partial x} \end{pmatrix} \quad \begin{pmatrix} 0 \\ 1 \\ 0 \\ \frac{\partial f}{\partial y} \end{pmatrix} \quad \begin{pmatrix} 0 \\ 0 \\ 1 \\ \frac{\partial f}{\partial z} \end{pmatrix}$$
$$\begin{pmatrix} 1 \\ 0 \\ 0 \\ x \end{pmatrix} \quad \begin{pmatrix} 0 \\ 1 \\ 0 \\ y \end{pmatrix} \quad \begin{pmatrix} 0 \\ 0 \\ 1 \\ -z \end{pmatrix}$$

Let  $\gamma = \left(\sqrt{\quad}\right)^{-1}$  we apply GS Method

$$W_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ x\gamma \end{pmatrix}$$

$$W_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ y\gamma \end{pmatrix} - \frac{\begin{pmatrix} 1 \\ 0 \\ 0 \\ x\gamma \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \\ y\gamma \end{pmatrix}}{1 + y^2\gamma^2} \begin{pmatrix} 1 \\ 0 \\ 0 \\ x\gamma \end{pmatrix}$$

$$= \begin{pmatrix} 0 \\ 1 \\ 0 \\ y\gamma \end{pmatrix} - \frac{xy\gamma^2}{1 + y^2\gamma^2} \begin{pmatrix} 1 \\ 0 \\ 0 \\ x\gamma \end{pmatrix}$$

$$= \begin{pmatrix} -\frac{xy\gamma^2}{1 + y^2\gamma^2} \\ 1 \\ 0 \\ \frac{xy + y^3\gamma^3 - x^2y\gamma^3}{1 + y^2\gamma^2} \end{pmatrix} \quad \frac{xy(1 + y^2\gamma^2) - x^2y\gamma^3}{1 + y^2\gamma^2}$$

$$\hat{W}_2 = \begin{pmatrix} -\frac{xy\gamma^2}{1 + y^2\gamma^2} \\ 1 \\ 0 \\ \frac{xy + y^3\gamma^3 - x^2y\gamma^3}{1 + y^2\gamma^2} \end{pmatrix}$$

$$W_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \\ -z\gamma \end{pmatrix} - \frac{\begin{pmatrix} 0 \\ 0 \\ 1 \\ -z\gamma \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \\ y\gamma \end{pmatrix}}{1 + y^2\gamma^2} - \frac{\begin{pmatrix} 0 \\ 0 \\ 1 \\ -z\gamma \end{pmatrix} \begin{pmatrix} -\frac{xy\gamma^2}{1 + y^2\gamma^2} \\ 1 \\ 0 \\ \frac{xy + y^3\gamma^3 - x^2y\gamma^3}{1 + y^2\gamma^2} \end{pmatrix}}{-11} \begin{pmatrix} \end{pmatrix}$$

$$= \begin{pmatrix} 0 \\ 0 \\ 1 \\ \gamma z \end{pmatrix} + \frac{\gamma^2 y z}{1 + \gamma^2 y^2} \begin{pmatrix} 0 \\ 1 \\ 0 \\ \gamma y \end{pmatrix} + \frac{\gamma z (\gamma y + \gamma^3 y^3 - \gamma^3 x^2 y)}{(\gamma y + \gamma^3 y^3 - \gamma^3 x^2 y)^2} \begin{pmatrix} -x y \gamma^2 \\ 1 + \gamma^2 y^2 \\ 0 \\ - \end{pmatrix}$$

Okay I agree not pretty, but it's clear that that can be calculated

For example for  $x=2, y=5, z=4, w=2\sqrt{2}$

Here  $\gamma = \frac{1}{15} \dots$

Or for  $x=1, y=2, z=0, w=\sqrt{11}$

We find

$$w_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 2 \end{pmatrix}$$

$$\gamma = \frac{1}{\sqrt{4}} = \frac{1}{2}$$

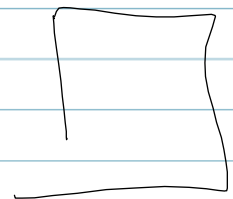
$$w_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$$

$$w_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

$$h_1 = \begin{pmatrix} \frac{1}{\sqrt{5}} \\ 0 \\ 0 \\ \frac{2}{\sqrt{5}} \end{pmatrix}$$

$$h_2 = w_2$$

$$h_3 = w_3$$





Note For some problems it suffices to know the normal vector to the hypersurface.

Here we can use the CROSS product

$$\det \begin{pmatrix} l_1 & l_2 & l_3 & l_4 \\ v_1 & \longrightarrow & & \\ v_2 & \longrightarrow & & \\ v_3 & \longrightarrow & & \end{pmatrix} = n$$

In our example

$$\begin{pmatrix} l_1 & 1 & 0 & 0 \\ l_2 & 0 & 1 & 0 \\ l_3 & 0 & 0 & 1 \\ l_4 & 2 & 0 & 0 \end{pmatrix}$$

$$\begin{aligned} &= l_1 \det \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 2 & 0 & 0 \end{pmatrix} - l_2 \det \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 2 & 0 & 0 \end{pmatrix} \\ &+ l_3 \det \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 2 & 0 & 0 \end{pmatrix} - l_4 \det \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \\ &= 2l_1 - 0l_2 + 0l_3 - l_4 = \begin{pmatrix} 2 \\ 0 \\ 0 \\ -1 \end{pmatrix} \end{aligned}$$

That it is easy to find normal or OVB

$$x_1 = \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} \quad x_2 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 2 \end{pmatrix} \frac{1}{\sqrt{5}}$$

$$x_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} \quad x_3 = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

which also span the tangent space!