

Last time The dual space of a vector space  $V$  is

$$V^* = \{ \ell: V \rightarrow \mathbb{R} \mid \ell \text{ linear} \} \cong \mathcal{L}(V, \mathbb{R}) \cong \text{Hom}(V, \mathbb{R}).$$

If  $B = \{b_1, \dots, b_n\}$  is a basis of a vector space  $V$  then

$B^* = \{b_1^*, \dots, b_n^*\}$ , where  $b_i^*: V \rightarrow \mathbb{R}$  is defined by

$$b_i^*(b_j) = \delta_{ij} = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases},$$

is a basis of  $V^*$

Hence if  $\dim V = n < \infty$ ,  $\dim V^* = n$ .

(Note:  $\dim W = n \iff \exists$  an isomorphism  $\psi: \mathbb{R}^n \rightarrow W$ )

So  $\dim V = n \implies V$  and  $V^*$  are isomorphic.

Concretely  $f: V \rightarrow V^*$   $f(\sum c_i b_i) = \sum c_i b_i^*$

is an isomorphism

The transpose of a matrix  $A$  is the matrix  $A^T$  with

$$(A^T)_{ij} = A_{ji} \quad \text{for all indices } i, j.$$

Exercise  $(AB)^T = B^T A^T$

Solution  $(AB)^T_{ij} = (AB)_{ji} = \sum_k A_{jk} B_{ki} = \sum_k (A^T)_{kj} (B^T)_{ik}$   
 $= \sum_k (B^T)_{ik} (A^T)_{kj} = (B^T A^T)_{ij}$  □

Given a linear map  $T: V \rightarrow W$  we have a linear map

$$T^*: W^* \rightarrow V^* \quad (\text{the book writes } T^t)$$

$$T^*(\ell) := \ell \circ T \quad \text{for all } \ell \in W^*.$$

We proved:

Lemma Let  $A$  be a basis of  $V$ ,  $A^*$  dual basis of  $V^*$

$B$  a basis of  $W$ ,  $B^*$  dual basis of  $W^*$  and  $T: V \rightarrow W$  a linear map. Then

$$[T^*]_{A^* B^*} = ([T]_{BA})^T$$

## Double duals

Given a vector space  $V$  we have a dual  $V^*$ . Since  $V^*$  is a vector space it has a dual  $(V^*)^* =: V^{**}$ .

Lemma 17.1 Suppose  $V$  is a finite dimensional vector space.

Then the map  $ev: V \rightarrow (V^*)^*$  defined by

$$(ev(v))(l) = l(v) \quad \text{for all } v \in V, l \in V^*$$

is a (natural) isomorphism.

Proof Step 1 For each  $v \in V$  we have a linear map

$$ev(v): V^* \rightarrow \mathbb{R}, \quad (ev(v))(l) = l(v).$$

Check  $\forall \lambda_1, \lambda_2 \in \mathbb{R}, l_1, l_2 \in V^*$

$$\begin{aligned} ev(v)(\lambda_1 l_1 + \lambda_2 l_2) &= (\lambda_1 l_1 + \lambda_2 l_2)(v) = \lambda_1 l_1(v) + \lambda_2 l_2(v) \\ &= \lambda_1 (ev(v)(l_1)) + \lambda_2 (ev(v)(l_2)) \end{aligned}$$

Step 2 The map

$$ev: V \rightarrow V^{**}, \quad v \mapsto ev(v)$$

is linear

Check  $\forall \lambda_1, \lambda_2 \in \mathbb{R}, v_1, v_2 \in V, \forall l \in V^*$

$$\begin{aligned} ev(\lambda_1 v_1 + \lambda_2 v_2)(l) &= l(\lambda_1 v_1 + \lambda_2 v_2) = \lambda_1 l(v_1) + \lambda_2 l(v_2) \\ &= \lambda_1 (ev(v_1)(l)) + \lambda_2 (ev(v_2)(l)) \\ &= (\lambda_1 ev(v_1) + \lambda_2 ev(v_2))(l) \end{aligned}$$

Since  $l \in V^*$  is arbitrary

$$ev(\lambda_1 v_1 + \lambda_2 v_2) = \lambda_1 ev(v_1) + \lambda_2 ev(v_2).$$

Step 3

$ev: V \rightarrow (V^*)^*$  is injective.

Check suppose  $ev(v) = 0$ . Fix a basis  $B = \{b_1, \dots, b_n\}$  of  $V$ .

Then  $v = \sum c_i b_i$  for some  $c_1, \dots, c_n \in \mathbb{R}$ .

if  $ev(v) = 0$ , then  $(ev(v))(l) = 0 \quad \forall l \in V^*$ .

In particular  $0 = (ev(v))(b_i^*) = b_i^*(v) = b_i^*(\sum c_j b_j)$

$$= \sum_j c_j b_i^*(b_j) = c_i.$$

$$\text{as } c_i = 0 \quad \forall i. \Rightarrow v = \sum c_i b_i = 0.$$

$$\Rightarrow N(ev) = \{0\}. \Rightarrow ev \text{ is injective.}$$

Finally,  $\dim V = n \Rightarrow \dim V^* = n \Rightarrow \dim (V^*)^* = n.$

$\Rightarrow ev: V \rightarrow (V^*)^*$  is an isomorphism  
(since it's injective).  $\square$

Recall If  $\{b_1, \dots, b_n\}$  is a basis of a vector space  $V$  then  $\forall v \in V$   
 $\exists$  unique scalars  $c_1, \dots, c_n \in V$  s.t.

$$v = \sum c_i b_i.$$

The scalars  $c_1, \dots, c_n$  depend on  $v$ ; they are functions

$$\text{of } v: \quad c_i = c_i(v). \quad \text{and} \quad v = \sum c_i(v) b_i.$$

Q. What are these functions  $c_i(v)$ ?

A.

if $v = b_1$ ,	$v = 1 \cdot b_1 + 0 \cdot b_2 + \dots + 0 \cdot b_n$
if $v = b_2$	$v = 0 \cdot b_1 + 1 \cdot b_2 + 0 \cdot b_3 + \dots + 0 \cdot b_n \dots$
if $v = b_j$	$v = 0 \cdot b_1 \dots 0 \cdot b_{j-1} + 1 \cdot b_j + \dots + 0 \cdot b_n$

$$\Rightarrow c_i(b_j) = \begin{cases} 0 & i \neq j \\ 1 & i = j. \end{cases}$$

We guess:  $c_i(v) = b_i^*(v).$

$$\text{check } b_i^*(v) = b_i^* \left( \sum_j c_j b_j \right) = \sum_j c_j b_i^*(b_j) = \sum_j c_j \delta_{ij} = c_i.$$

We have proved: Lemma 17.2 Let  $B = \{b_1, \dots, b_n\}$  be a basis of  $V$ . Then  $\forall v \in V$   
 $v = \sum b_i^*(v) b_i$  where  $\{b_1^*, \dots, b_n^*\}$  is the dual basis.

Remark In lecture 10 we saw that a choice of a basis

$B = \{b_1, \dots, b_n\}$  of a vector space  $V$  defines an iso

$$\psi: \mathbb{R}^n \rightarrow V, \quad \psi \left( \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix} \right) = \sum c_i b_i.$$

$\psi$  has an inverse  $\Phi: V \rightarrow \mathbb{R}^n, \quad \Phi(v) = [v]_B$

$$\phi(\sum c_i b_i) = [\sum c_i b_i]_{\mathcal{B}} = \begin{pmatrix} c_1 \\ \vdots \\ c_n \end{pmatrix}$$

Lemma 17.2 says:  $[v]_{\mathcal{B}} = \begin{pmatrix} b_1^*(v) \\ \vdots \\ b_n^*(v) \end{pmatrix}$

Multilinear maps (see section 4.5 of text for a special case)

Definition Let  $V_1, \dots, V_k$  be vector spaces. A function

$$\omega: V_1 \times \dots \times V_k \rightarrow \mathbb{R}$$

is k-linear if it's linear in each variable:  $\forall i \in \{1, \dots, k\}$

$\forall \lambda, \mu \in \mathbb{R}, v_i \in V_i, \dots, v_{i-1} \in V_{i-1}, u, w \in V_i, v_{i+1} \in V_{i+1}, \dots$

$$\omega(v_1, \dots, v_{i-1}, \lambda u + \mu w, v_{i+1}, \dots, v_k) = \lambda \omega(v_1, \dots, v_{i-1}, u, v_{i+1}, \dots, v_k)$$

$$+ \mu \omega(v_1, \dots, v_{i-1}, w, v_{i+1}, \dots, v_k)$$

If  $k=2$  we say  $\omega$  is a bilinear.

Ex The standard inner product  $(\cdot, \cdot): \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}$

$$(x, y) := \sum_{i=1}^n x_i y_i$$

is bilinear.

Ex For any vector space  $V$ , the map

$$\langle \cdot, \cdot \rangle: V^* \times V \rightarrow \mathbb{R} \quad \langle l, v \rangle = l(v)$$

is bilinear.

Ex  $D: \mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R} \quad D\left(\begin{pmatrix} a \\ b \end{pmatrix}, \begin{pmatrix} c \\ d \end{pmatrix}\right) = ad - bc$

is bilinear.

Ex  $D: \mathbb{R}^3 \times \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}$

$$D\begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & \dots & \dots \end{pmatrix} = \det \begin{pmatrix} a_{11} & a_{12} & \dots \\ a_{21} & \dots & \dots \\ a_{31} & \dots & \dots \end{pmatrix} \text{ is 3-linear.}$$

Remark Multilinear maps are sometimes called tensors.