

Compressed Sensing of Continuous Index Signals and of Low Rank Matrices

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Outline

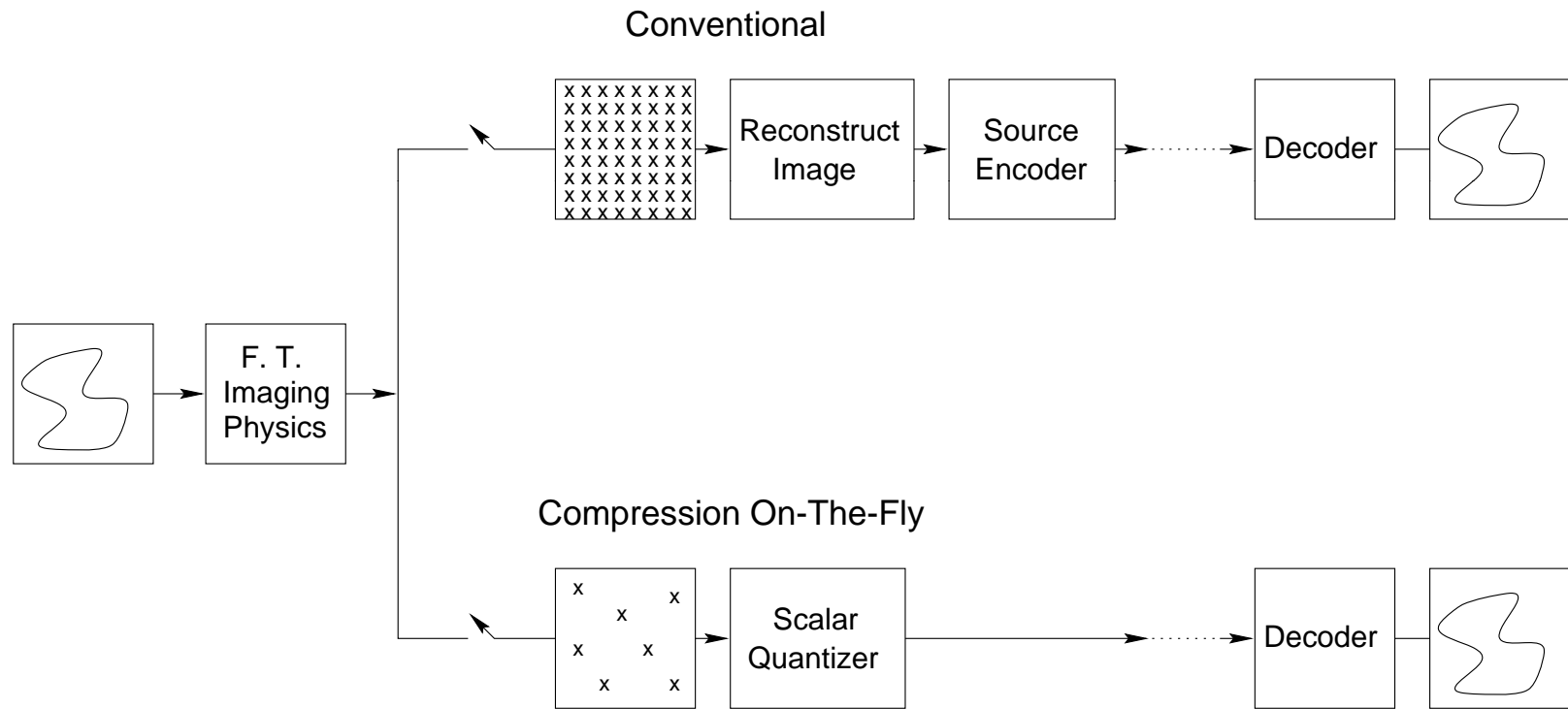
- Part I: compressive sensing of continuous-index signals (work with Ping Feng and Raman Venkataramani)
- Part II: Guaranteed low-rank matrix approximation from linear observations (work with Kiryung Lee)

Applications:

Real-world Signals are continuous indexed:

- Communications
- ELINT
- Fourier imaging: MRI, CT, SAR
 - Sparse image $X(f)$ $f \in \mathbb{R}^d$
 - Sampling in $t \in \mathbb{R}^d$

Compression On-The-Fly



Spectrum-Sparse Continuous-Index Signals

- 1-D continuous-time signals

$$x(t) \leftrightarrow X(f) \quad t, f \in \mathbb{R}$$

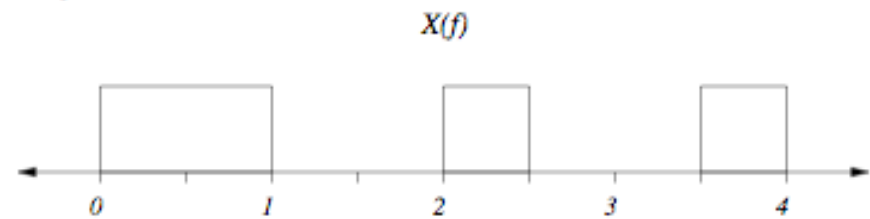
- 1-D discrete-time signals (infinite sequences)

$$x(n) \leftrightarrow X(f) \quad n \in \mathbb{Z}, \quad f \in \mathbb{R}$$

Spectrum-Sparse:

$$X(f) = 0, \quad f \notin \mathcal{F}, \quad \mathcal{F} = \bigcup_{i=1}^n [a_i, b_i) \subseteq [f_{\min}, f_{\max}]$$

$$\frac{\lambda(\mathcal{F})}{f_{\max} - f_{\min}} \leq \Omega < 1$$



Questions

- Sampling rate requirements ?
 - Known \mathcal{F}
 - Unknown \mathcal{F}
- Sampling at the minimum rate ?
 - Design of sampling scheme
 - Reconstruction
- How achieve:
 - Universal (non-adaptive sampling)
 - Perfect (or robust) reconstruction
 - Computation linear in the data size
- Relationship to compressive sensing?

Sampling Rate

Throw in the towel (sufficient condition)

- Nyquist sampling: $f_{\text{Nyq}} = f_{\text{max}} - f_{\text{min}}$

Necessary conditions

- Landau lower bound (1967) $D^- \geq \lambda(\mathcal{F})$
 - Arbitrary pointwise sampling
 - Sufficient for **known** \mathcal{F} packable or not (Kahn & Liu, 1965)

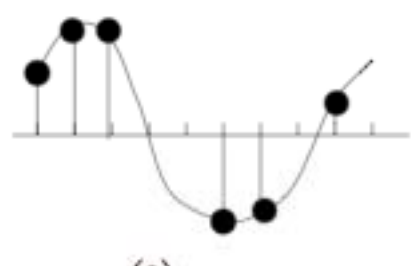
$$D^- \approx \lambda(\mathcal{F}) \leq \Omega f_{\text{Nyq}}$$

Sufficient conditions, **unknown** \mathcal{F} (Feng & Bresler, 1996):

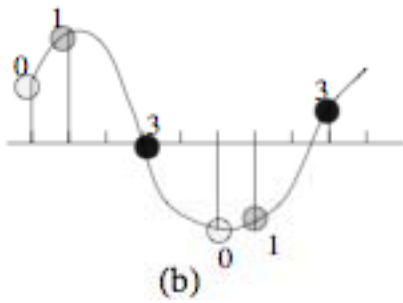
$$D^- \approx \begin{cases} 2\Omega f_{\text{Nyq}} & \text{for all signals} \\ \Omega f_{\text{Nyq}} & \text{for almost all signals} \end{cases}$$

Periodic Sampling

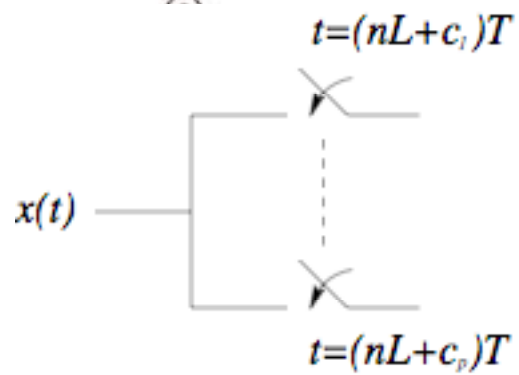
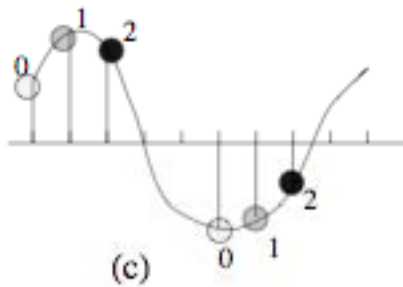
Non-uniform sampling
(not representable by cosets)



Multicoset sampling
Cosets = 0, 1, 3



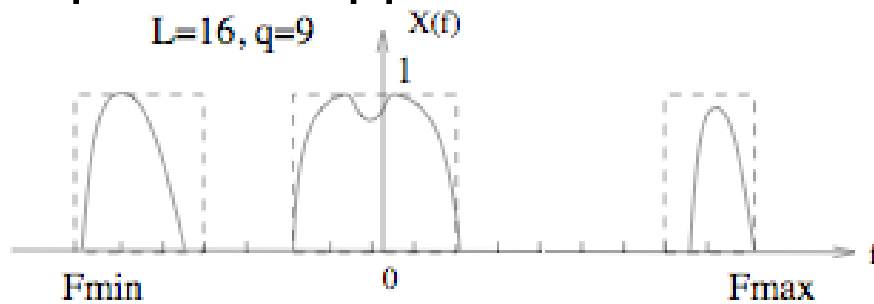
Bunched sampling
Cosets = 0, 1, 2



$$\frac{1}{T} \geq f_{Nyq}$$

- (L, p) sampling pattern: $\mathcal{C} = \{c_i : 1 \leq i \leq p\}$
- Period = L

Spectral support at resolution L



Active spectral cells:

$$\mathcal{F}_i \cap \mathcal{F} \neq \emptyset, i = 1, 2, \dots, q$$

$$\Omega_L \triangleq \frac{q}{L} \approx \Omega$$

$$\mathcal{F}_0 = \left[0, \frac{1}{LT}\right], \quad \mathcal{F}_l \triangleq \mathcal{F}_0 + l/L, \quad l = 1, 2, \dots, L-1,$$

Vectorized signal
spectrum

$$X_l(f) \triangleq X\left(f + \frac{l}{LT}\right) \chi(f; \mathcal{F}_0)$$

$$\zeta(f) \triangleq [X_1(f), \dots, X_L(f)]', \quad f \in \mathcal{F}_0$$

Vectorized
sample
spectrum

$$x_i(m) = x(Lm + c_i), \quad m \in \mathbb{Z} \leftrightarrow X_i(f)$$

$$\mathbf{y}(f) \triangleq LT[e^{-j2\pi c_1 f T} X_1(LTf), \dots, e^{-j2\pi c_p f T} X_p(LTf)]',$$

$$\mathbf{y}(f) = \mathbf{A}\zeta(f), \quad f \in \mathcal{F}_0, \quad \mathbf{A} \in \mathbb{C}^{p \times L} = \begin{array}{l} \text{Submatrix of} \\ \text{DFT } L \times L \end{array}$$

Blind Reconstruction & Compressive Sensing

$$\mathbf{y}(f) = \mathbf{A}\zeta(f), \quad f \in \mathcal{F}_0, \quad \mathbf{A} \in \mathbb{C}^{p \times L} = \text{Submatrix of DFT}$$

$$\|\zeta(f)\|_0 \leq \Omega_L L, \quad f \in \mathcal{F}_0$$

$$\mathbf{P0:} \text{ for each } f \in \mathcal{F}_0 \quad \min_{\zeta(f)} \|\zeta(f)\|_0$$

subject to $\mathbf{y}(f) = \mathbf{A}\zeta(f)$

- Common sparsity pattern for all $f \in \mathcal{F}_0$
- Simultaneous sparse approximation (Rao *et al* 2005, Chen & Huo 2006, Tropp *et al*, 2006)
- *But, uncountably infinite number of simultaneous measurement vectors*

Spectral Support Recovery

- Active spectral cell indices:

$$\mathbf{k} = [k_1, k_2, \dots, k_q]' : \mathcal{F}_{k_r} \cap \mathcal{F} \neq \emptyset,$$

$$k_r \in \{1, 2, \dots, L\} \quad r = 1, \dots, q,$$

$$\mathbf{P1:} \quad \hat{\mathbf{k}} = \arg \min_{\|\mathbf{k}\|_0=q} \int_{f \in \mathcal{F}_0} \|\mathbf{P}_{\text{Range}^\perp(\mathbf{A}_{\mathbf{k}})} \mathbf{y}(f)\|_2^2 df$$

$$\mathbf{P2:} \quad \hat{\mathbf{k}} = \arg \min_{\|\mathbf{k}\|_0=q} \text{tr}(\mathbf{P}_{\text{Range}^\perp(\mathbf{A}_{\mathbf{k}})} \mathbf{R})$$

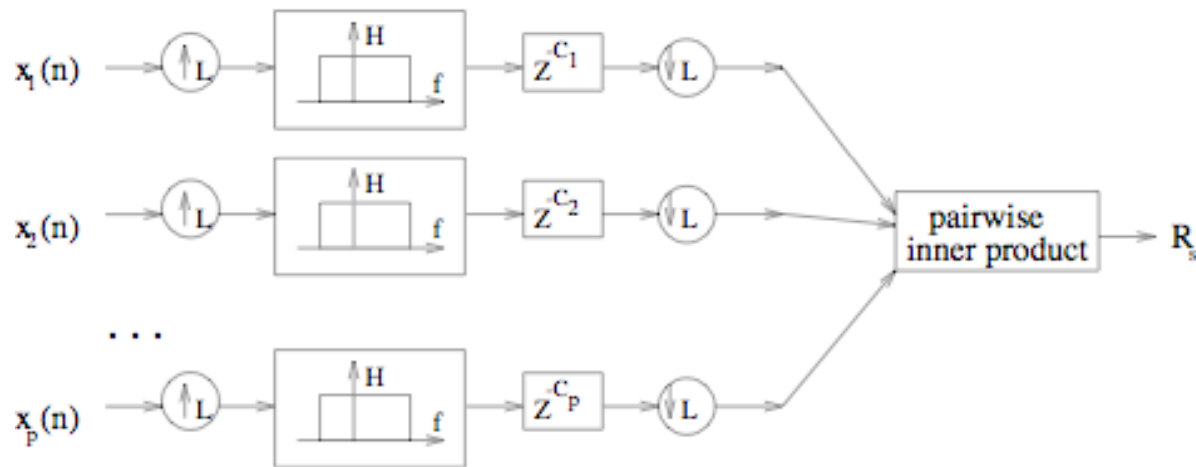
$$\mathbf{R} \triangleq \int_{f \in \mathcal{F}_0} \mathbf{y}(f) \mathbf{y}^*(f) df$$

$$(\mathbf{R})_{kl} = \left\langle x_k \left(n - \frac{c_k}{L} \right), x_l \left(n - \frac{c_l}{L} \right) \right\rangle.$$

- Finite dimensional problem!

Finite-dimensional optimization

$$\mathbf{P2: } \hat{\mathbf{k}} = \arg \min_{q, \|\mathbf{k}\|_0=q} \text{tr} [\mathbf{P}_{\text{Range}^\perp(\mathbf{A}_k)} \mathbf{R}]$$



- Solution of P2 using greedy algorithm (Feng & Bresler, 1996; Venkataramani & Bresler, 1998)

More equivalent problems

P3: Given $\mathbf{R} \in \mathbb{C}^{p \times p}$ find the smallest integer q and spectral cell index vector \mathbf{k} of length q such that $\mathbf{R} = \mathbf{A}_{\mathbf{k}} \mathbf{Z} \mathbf{A}_{\mathbf{k}}^*$ for some $\mathbf{Z} \in \mathbb{C}^{q \times q}$, $\mathbf{Z} \succeq 0$

- Let $\mathbf{R} = \mathbf{U}_s \Lambda_s \mathbf{U}_s^*$, $\mathbf{U} \in \mathbb{C}^{p \times r}$, $r = \text{rank}(\mathbf{R}) = \text{rank}(\mathbf{Z})$

P4: Given \mathbf{U} find the smallest integer q and spectral cell index vector \mathbf{k} of length q such that

$$\mathbf{U} = \mathbf{A}_{\mathbf{k}} \mathbf{Q} \text{ for some } \mathbf{Q} \in \mathbb{C}^{q \times q}$$

- **Proposition:** Problems P0 -- P4 are equivalent
- P4 is the (now) classical MMV problem!
- Mishali+Eldar (2007) proposed to solve it using MMV compressed sensing methods.

Sampling Conditions

Theorem (Feng & Bresler, 1996). Let \mathcal{X} consist of signals with spectral support of spectral occupancy at most Ω_L at resolution L . Then

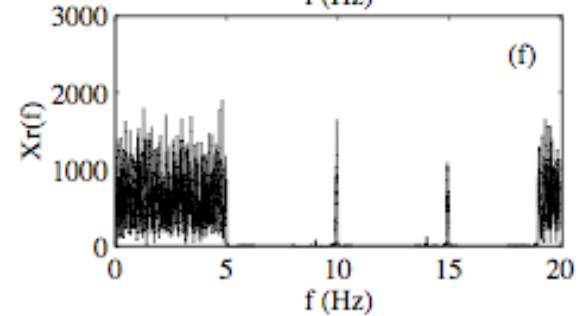
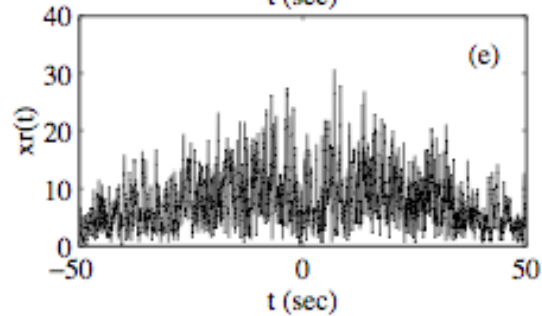
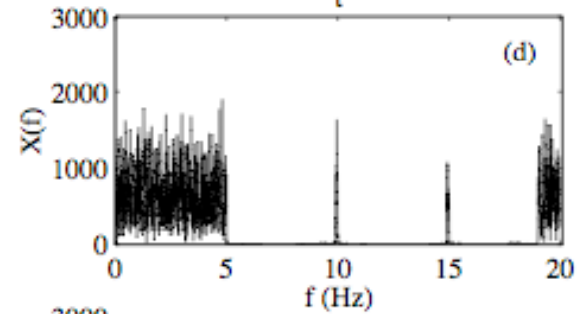
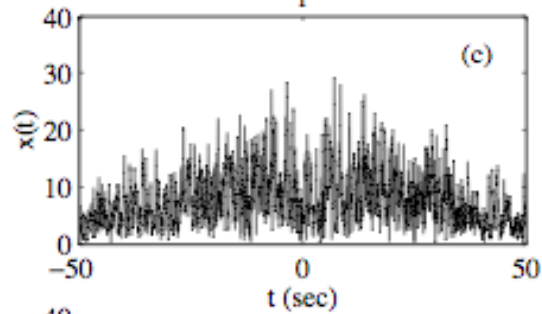
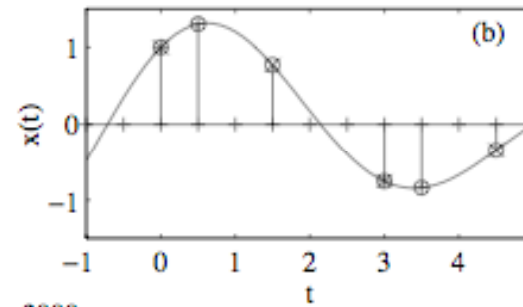
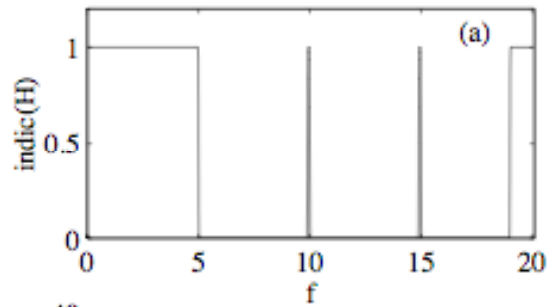
- (1) all signals in \mathcal{X} can be uniquely reconstructed from their samples on a periodic pattern with average rate $\approx 2\Omega_L f_{\max}$
- (2) almost all signals in \mathcal{X} can be reconstructed from samples at rate $\approx \Omega_L f_{\max}$.

Proof: (1) For bunched pattern with $p \geq 2q + 1$

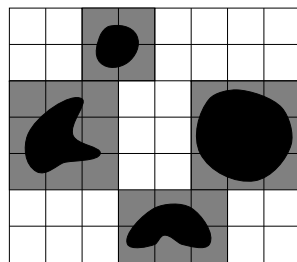
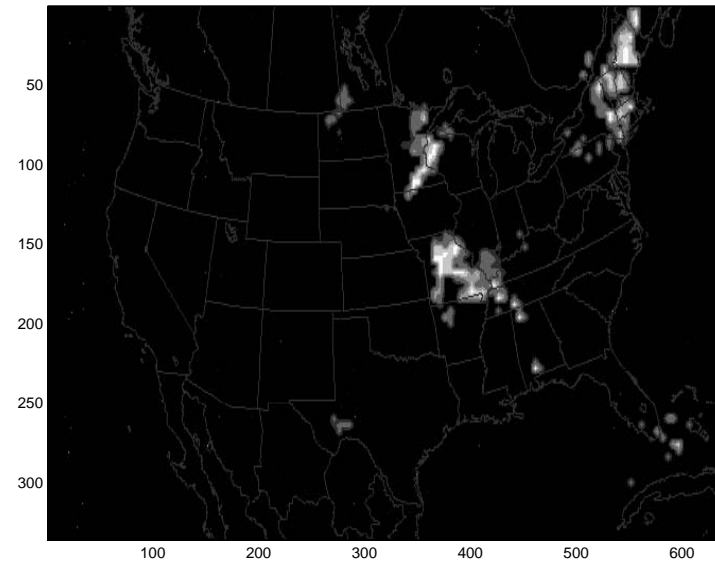
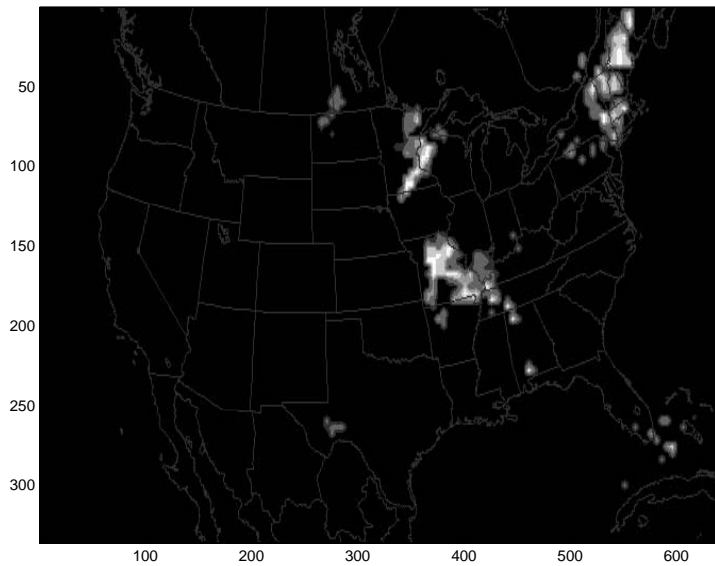
$$\text{Spark}(\mathbf{A}) \geq 2q + 1$$

(b) Almost all \mathbf{Z} have full rank.

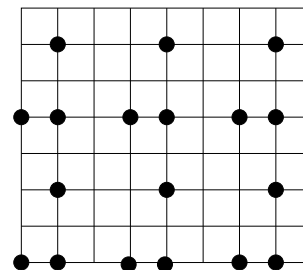
Numerical Experiments



2D Spectrum-Blind Sampling*



(a)



(b)

* IICIP 1998

Conclusions

- Spectrum-Blind sampling generalizes Compressed Sensing, and reduces the infinite dimensional problem to a finite dimensional problem without discretization.
- Compressed sensing with DFT measurement and time-sparse signals in Euclidean spaces is a special case of spectrum-blind sampling.
- Compressed Sensing theory provides new insights and provable, efficient techniques to solve the spectrum-blind sampling problem.

Guaranteed Low-Rank Matrix Approximation from Linear Observations

Work with Kiryung Lee

ECE/CSL UIUC

$$\mathcal{A} : \mathbb{C}^{m \times n} \rightarrow \mathbb{C}^p, X \in \mathbb{C}^{m \times n}, y \in \mathbb{C}^p$$

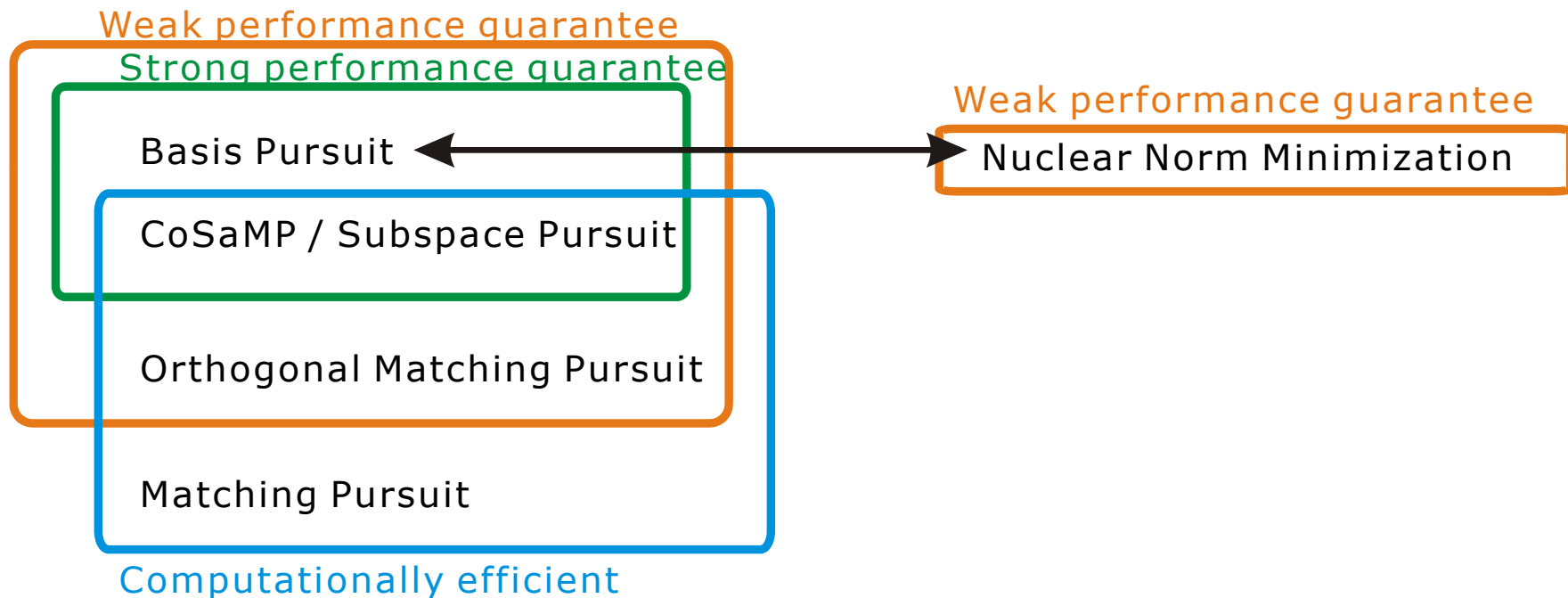
$$y = \mathcal{A}X + v,$$

$$\min \text{rank}(X), \text{ subject to } \|y - \mathcal{A}X\|_2 < \varepsilon$$

Rank Minimization: Analogy – Previous Works

ℓ_0 -Norm Minimization

Rank Minimization

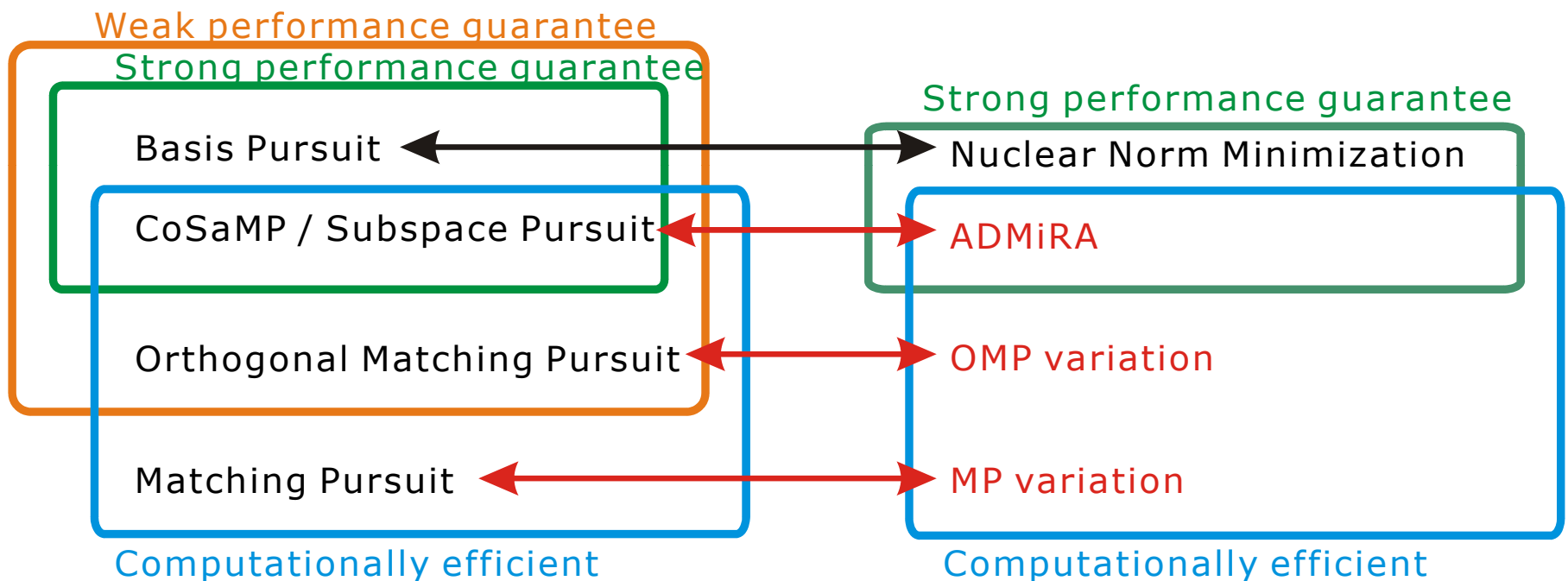


Performance guarantee	Sparsity (or low-rank)	Measurements
Weak	Exact	Exact - noiseless
Strong	Approximate	Noisy

Rank Minimization: Analogy – New Contribution

ℓ_0 -Norm Minimization

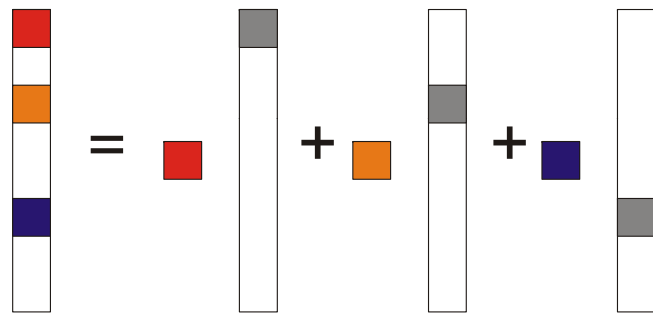
Rank Minimization



Performance guarantee	Sparsity (or low-rank)	Measurements
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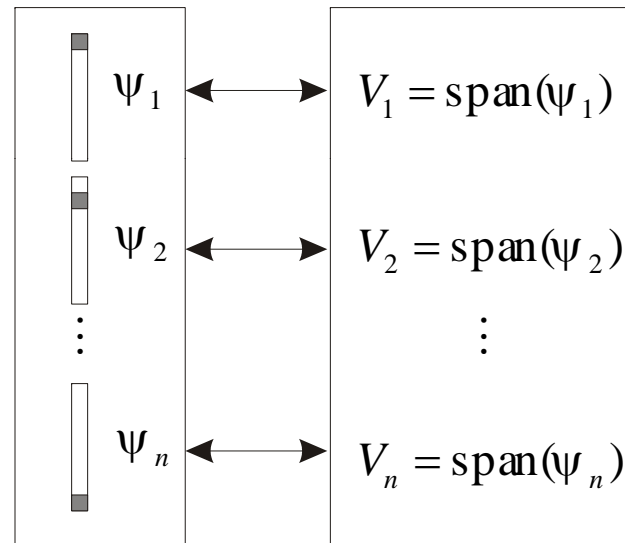
Vector Atomic Decomposition

$$x \in \mathbb{C}^n$$



$$x = c_1 \psi_i + c_2 \psi_j + c_3 \psi_k$$

⊙: set of atoms Δ: set of atomic spaces



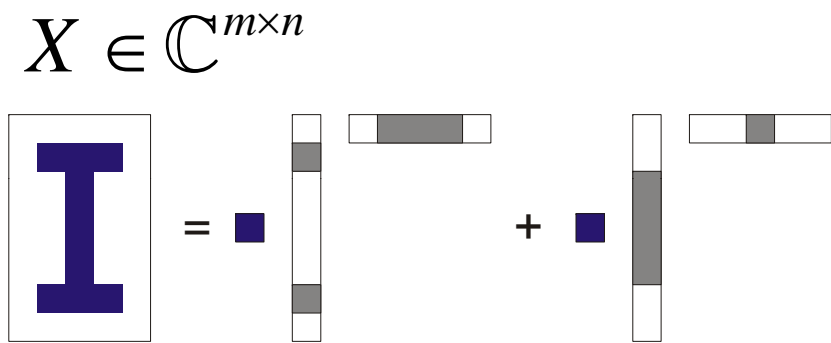
finite

$\|x\|_0 \leq s$ iff x is spanned by s atoms

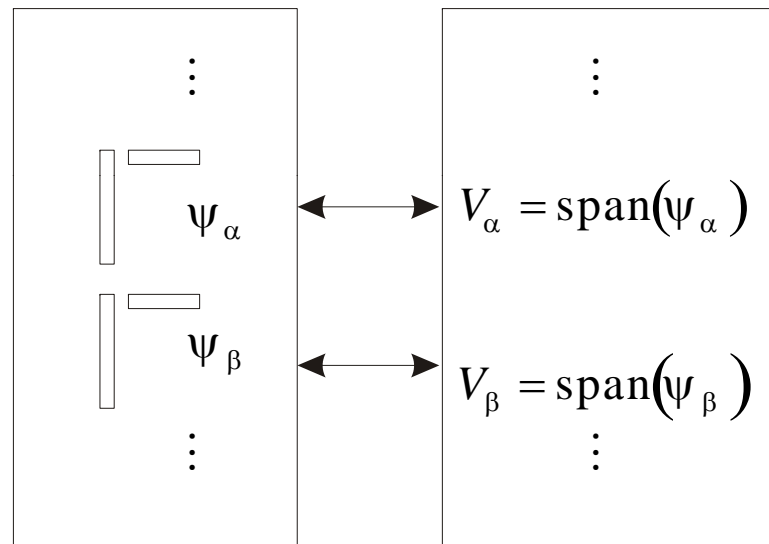
$$x \in \bigcup_{i=1}^n \left(\sum_{k=1}^s V_{i_k} \right) = \bigcup_{i=1}^n \text{span} \left(\{ \psi_{i_k} \}_{k=1}^s \right)$$

Matrix Atomic Decomposition

\mathbb{O} : set of atoms \mathbb{A} : set of atomic spaces



$$X = c_1 \psi_\alpha + c_2 \psi_\beta$$



uncountably infinite

$\text{rank}(X) \leq r$ iff X is spanned by r atoms

$$X \in \bigcup_{|\Gamma| \leq r} \left(\sum_{\alpha \in \Gamma} V_\alpha \right) = \bigcup_{\Psi \subset \mathbb{O}, |\Psi| \leq r} \text{span}(\Psi)$$

Vector Correlation Maximization

$$A \in \mathbb{C}^{p \times n}, y \in \mathbb{C}^p$$

a_k : k -th column of A

e_k : k -th column of I_n ($n \times n$ identity matrix)

P_{e_k} : projection onto $\text{span}(e_k)$

$$|\langle y, a_k \rangle| = |\langle y, A e_k \rangle| = |\langle A^H y, e_k \rangle| = \|P_{e_k} A^H y\|_2$$

Find a column a_k that maximizes the correlation

\Leftrightarrow Find an atom e_k that maximizes $\|P_{e_k} A^H y\|_2$

Matrix Correlation Maximization

$$\mathcal{A} : \mathbb{C}^{m \times n} \rightarrow \mathbb{C}^p, y \in \mathbb{C}^p$$

\mathcal{A}^* : adjoint of \mathcal{A}

ψ : an atom

P_ψ : projection onto $\text{span}(\psi)$

$$|\langle y, \mathcal{A}\psi \rangle| = |\langle \mathcal{A}^* y, \psi \rangle| = \|P_\psi \mathcal{A}^* y\|_F$$

Find an atom ψ that maximizes the correlation $|\langle y, \mathcal{A}\psi \rangle|$

\Leftrightarrow Find an atom ψ that maximizes $\|P_\psi \mathcal{A}^* y\|$

- Can be done by SVD of matrix $\mathcal{A}^* y$

Matrix Correlation Maximization

- Greedy algorithms (MP, OMP, CoSaMP, SP) are extended from the vector case to the matrix case
- In particular, we propose **ADMIRA**
(= **A**tomic **D**ecomposition for **M**inimum **R**ank **A**pproximation)
that is **efficient** in computation and has a **performance guarantee**.

ADMiRA

- Analogous to CoSaMP/SP
- Iterative subspace selection
- Assumptions
 - Target rank is fixed to r
 - Linear operator satisfies RIP: $\delta_{7r} < 0.056$
 - Measurement is obtained by $b = \mathcal{A}X + v$

ADMIRA

- Performance guarantee
 - After $6(r+1)$ iterations, ADMIRA provides a rank- r approximation satisfying

$$\|X - \hat{X}\|_F \leq 20 \left(\|X - X_r\|_F + \frac{1}{\sqrt{r}} \|X - X_r\|_* + \|v\|_2 \right)$$

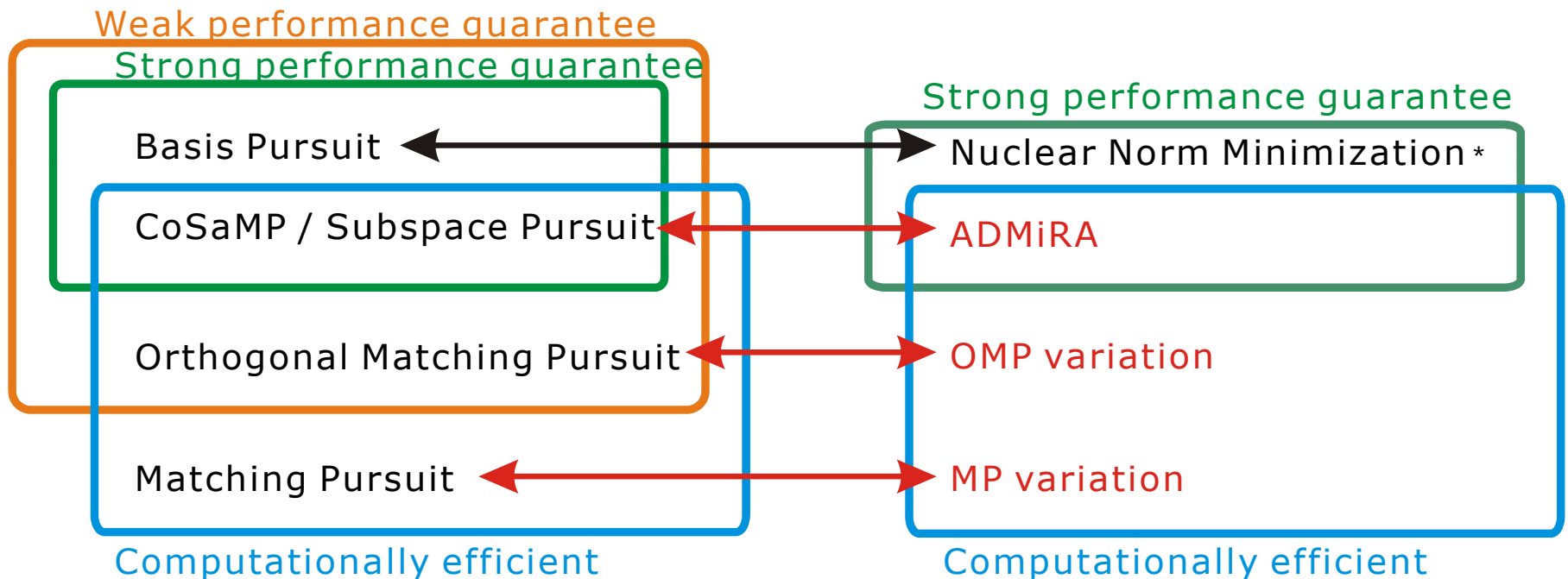
X_r : best rank- r approximation, $\| \cdot \|_*$: nuclear norm

- Efficient computation
 - most computation is (truncated) SVD
 - Randomized algorithms are applicable

Rank Minimization: Analogy – New Contribution

ℓ_0 -Norm Minimization

Rank Minimization



Performance guarantee	Sparsity (or low-rank)	Measurements
Weak	Exact	Exact - noiseless
Strong	Approximate	Noisy

* Note: after the presentation we learned about the paper by M. Fazel, E. Candès, B. Recht, & P. Parrilo, "Compressed Sensing and Robust Recovery of Low Rank Matrices," Asilomar Conference, Nov. 2008, which also presented a strong performance guarantee for nuclear norm minimization, although with different constants than ours.