

**Section 3.5 Exercise 5:**

a) The transition matrix from  $[e_1, e_2, e_3]$  to  $[u_1, u_2, u_3]$  is

$$A = \begin{pmatrix} 1 & 1 & 2 \\ 1 & 2 & 3 \\ 1 & 2 & 4 \end{pmatrix}^{-1} = \begin{pmatrix} 2 & 0 & -1 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{pmatrix}.$$

b) The coordinates wrt  $[u_1, u_2, u_3]$  are:

i)  $A(3, 2, 5)^T = (1, -4, 3)^T$ ; ii)  $A(1, 1, 2)^T = (0, -1, 1)^T$ ; iii)  $A(3, 3, 2)^T = (2, 2, -1)^T$ .

□

**Section 3.6 Exercise 10:**

Recall that dimension of row space equals to the dimension of column space and that row equivalent matrices have the same rank, we have  $\text{rank of } A = \text{rank of } U = 2$ . Also notice that  $\mathbf{a}_1$  and  $\mathbf{a}_2$  are linear independent, hence  $\mathbf{a}_3$  and  $\mathbf{a}_4$  are linear combinations of  $\mathbf{a}_1$  and  $\mathbf{a}_2$ . Thus we can write  $\mathbf{a}_3 = x\mathbf{a}_1 + y\mathbf{a}_2$ ,  $\mathbf{a}_4 = z\mathbf{a}_1 + w\mathbf{a}_2$  for some  $x, y, z, w \in \mathbb{R}$ :

$$A = \begin{pmatrix} -3 & 4 & -3x + 4y & -3z + 4w \\ 5 & -3 & 5x - 3y & 5z - 3w \\ 2 & 7 & 2x + 7y & 2z + 7w \\ 1 & -1 & x - y & z - w \end{pmatrix}$$

Now since  $A$  and  $U$  are row equivalent, they have the same row space. Thus  $(-3, 4, -3x + 4y, -3z + 4w)$ ,  $(5, -3, 5x - 3y, 5z - 3w)$  are linear combinations of  $(1, 0, 2, 1)$  and  $(0, 1, 1, 4)$ . We have  $(-3, 4, -3x + 4y, -3z + 4w) = a(1, 0, 2, 1) + b(0, 1, 1, 4)$  and  $(5, -3, 5x - 3y, 5z - 3w) = c(1, 0, 2, 1) + d(0, 1, 1, 4)$  for some  $a, b, c, d \in \mathbb{R}$ . Comparing the first two coordinates in these two equations, we see immediately that  $a = -3, b = 4, c = 5, d = -3$ . Substituting them back and looking the rest two coordinates, we have

$$\begin{aligned} -3x + 4y &= 2 \cdot (-3) + 1 \cdot (4) \\ -3z + 4w &= 1 \cdot (-3) + 4 \cdot (4) \\ 5x - 3y &= 2 \cdot (5) + 1 \cdot (-3) \\ 5z - 3w &= 1 \cdot (5) + 4 \cdot (-3). \end{aligned}$$

Solving these equations, we have  $x = 2, y = 1, z = 1, w = 4$ . Therefore  $\mathbf{a}_3 = (-2, 7, 11, 1)^T$  and  $\mathbf{a}_4 = (13, -7, 30, -3)^T$ . □

**Section 3.6 Exercise 22:**

a) To show the column space of  $C = AB$  is a subspace of the column space of  $A$ , it suffices to show that each column vector of  $C$  is a linear combination of column vectors of  $A$ . Now let  $\mathbf{b}_i$  be the  $i$ -th column vector of  $B$ . Then we know the  $i$ -th column vector of  $C = AB$  is  $A\mathbf{b}_i$ . (See textbook page 38). Now we write  $A = (\mathbf{a}_1, \dots, \mathbf{a}_n)$  where

each  $\mathbf{a}_i$  is a column vector. And write down  $\mathbf{b}_i = (b_{i1}, \dots, b_{in})^T$  explicitly. In this way, we have  $A\mathbf{b}_i = b_{i1}\mathbf{a}_1 + \dots + b_{in}\mathbf{a}_n$  which is a linear combination of column vectors of  $A$ . Thus we proved **a**.

**b)** We can prove this in two ways. First we can prove it similar to **a)**. Or we can apply **a)** to  $C^T = B^T A^T$ . The fact that column space of one matrix is the row space of its transpose gives us a second proof.

**c)** By **a)** Column rank of  $C \leq$  Column rank of  $A$ . By **b)** Row rank of  $C \leq$  Row rank of  $B$ . In fact we know that rank = column rank = row rank. Thus  $\text{rank}(C) \leq \min\{\text{rank}(A), \text{rank}(B)\}$ .  $\square$

### Section 4.1 Exercise 3:

We have  $L(\mathbf{0}) = \mathbf{a}$ , which is a given nonzero vector. Hence  $L$  can not be a linear transformation.  $\square$

### Section 4.1 Exercise 8:

**a) Yes:**  $L(aA + B) = C(aA + B) + (aA + B)C = aCA + CB + aAC + BC = a(CA + AC) + (CB + BC) = aL(A) + L(B)$ .

**b) Yes:** Similar computation.

**c) No, in general:** If  $L$  were a linear operator, then we have  $0 = L(I + (-I)) = L(I) + L(-I) = I^2C + (-I)^2C = 2C$ , which isn't always true. In fact,  $L$  is a linear operator if and only if  $C = 0$ , the zero matrix.  $\square$

### Section 4.1 Exercise 16:

Let's verify:

$$\begin{aligned} L(a\mathbf{u}_1 + \mathbf{u}_2) &= \mathbf{L}_2(\mathbf{L}_1(a\mathbf{u}_1 + \mathbf{u}_2)) && \text{because } L = L_2(L_1) \\ &= L_2(aL_1(\mathbf{u}_1) + \mathbf{L}_1(\mathbf{u}_2)) && \text{because } L_1 \text{ is a linear operator} \\ &= aL_2(L_1(\mathbf{u}_1)) + \mathbf{L}_2(\mathbf{L}_1(\mathbf{u}_2)) && \text{because } L_2 \text{ is a linear operator} \\ &= aL(\mathbf{u}_1) + \mathbf{L}(\mathbf{u}_2) && L = L_2(L_1). \end{aligned}$$

Thus  $L$  is a linear operator.  $\square$